
SMALL MASS ASSISTING MANNED MERCHANT VESSELS: THE ANTI-GROUNDING USE CASE

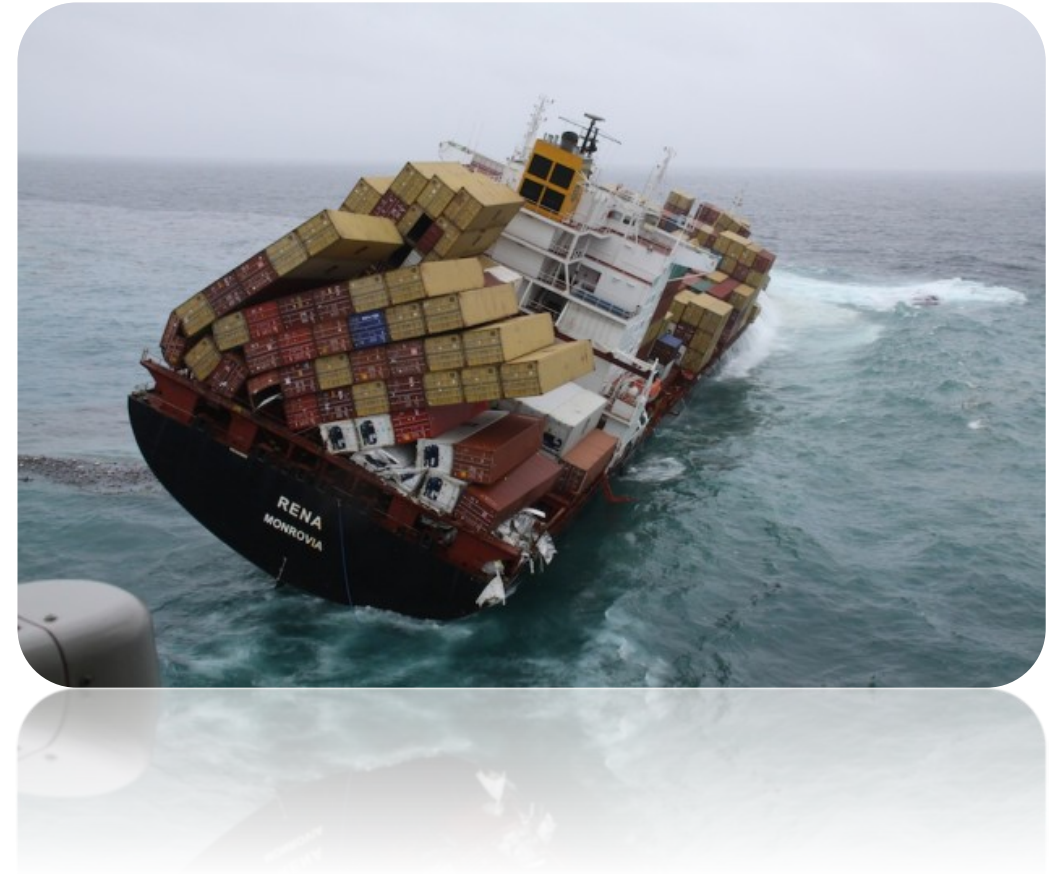
Vincent E. Schneider, Fraunhofer CML

14.11.2019, MTEC/ ICMAS2019 – Autonomous Vessels - Navigation



Why anti-grounding?

Between 2011 and 2015, more than
1,426 grounding accidents in
European waters [1]



Why anti-grounding?

51 groundings in the river Elbe [1],



Why anti-grounding?

51 groundings in the river Elbe [1],
40% thereof in port of Hamburg [2]



Agenda

- 1 Why anti-grounding and how to prevent it
- 2 The anti-grounding use case
- 3 Virtual Full Scale Simulation

How to prevent it?

Problems

Shallow riverbeds and tidal bore restrict passage

Sea Charts only display normed water depth

Recurring sedimentation requires frequent bottom mapping

Current approach

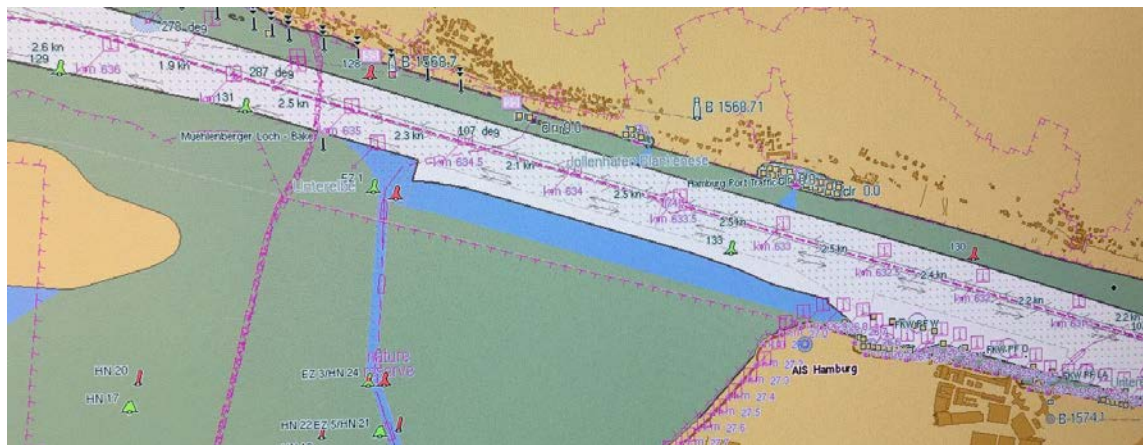
Weekly, for important areas daily depth measurements

Requires fleet of ships



Sea chart

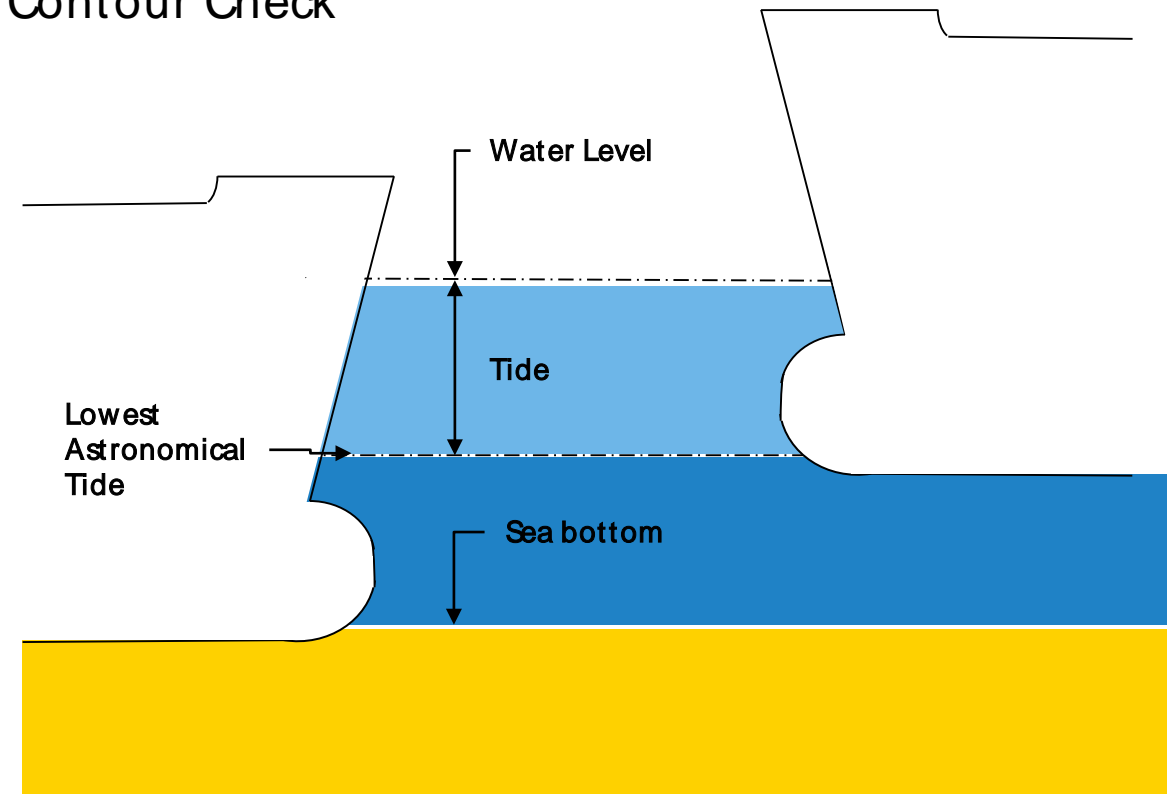
The drawback of LAT-based safety features in tidal waters



ECDIS Safety
Contour Check



Tidal reality



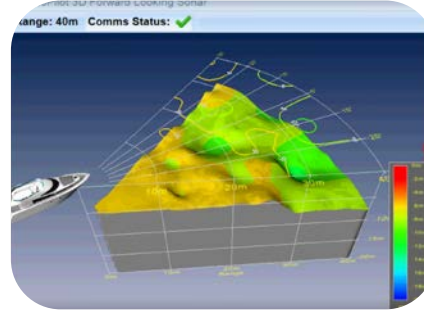
Current technologies



Hydrography
maps



Low time
resolution



Forward
looking sonar



ASV



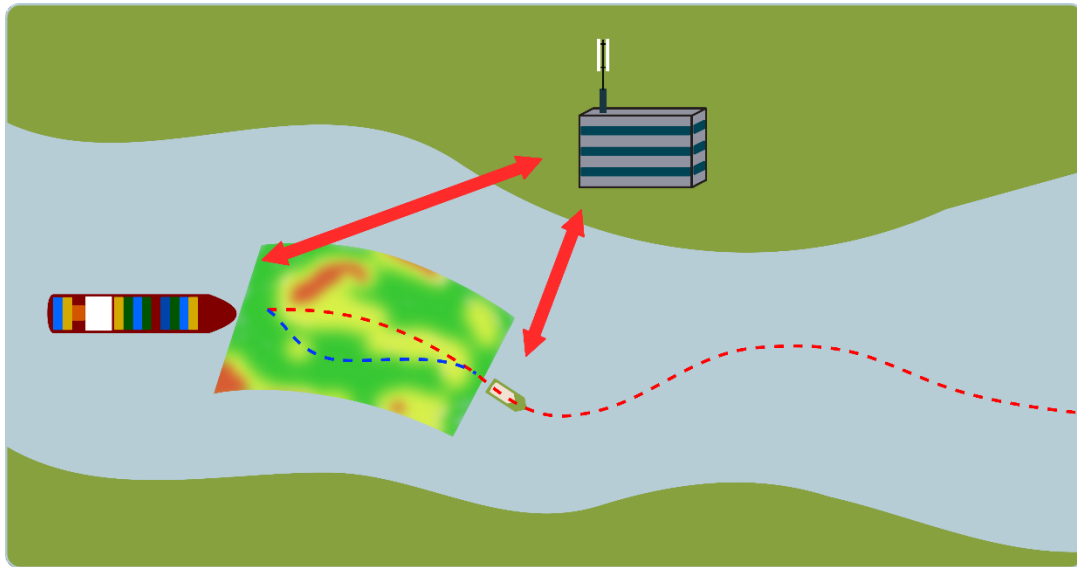
Shallow
water depth



Better time
resolution

The anti-grounding use case

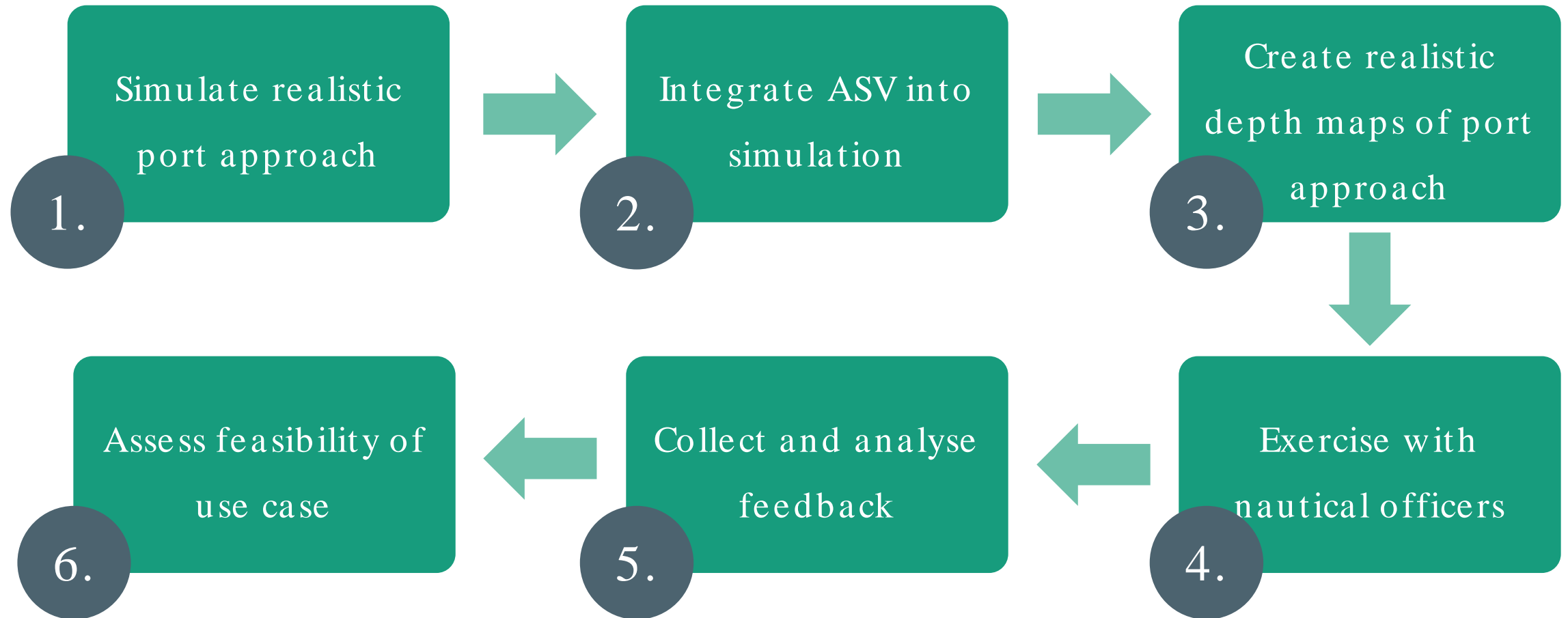
how a real-time solution could look like



1. Ship on port approach
2. ASV creating map
3. Ship avoids shallow water

Virtual Full Scale Simulations

early stage testing of system integration



Virtual Full Scale Simulation

1. Simulate realistic port approach



Stealth View

function:
free perspective



Simulation Centre

function:
ENC- und 3D-modeling



OsMan-Standalone

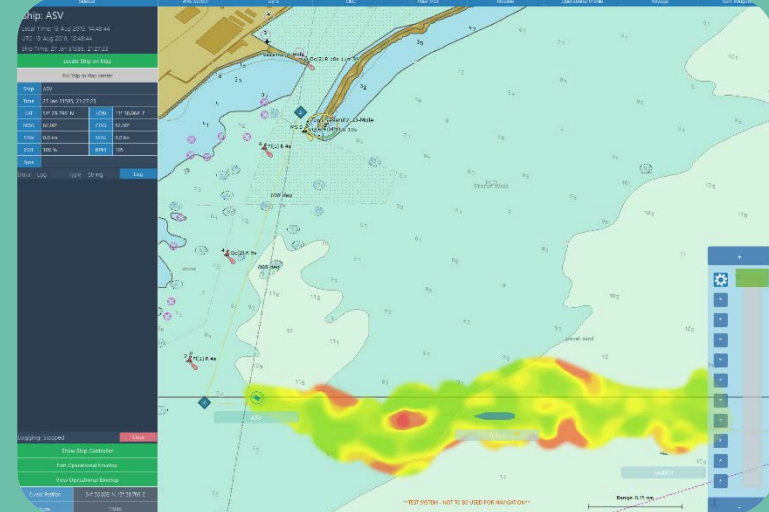
function:
modeling of own ship models

Virtual Full Scale Simulation

2. Integrate ASV into simulation



Ship Handling Simulator



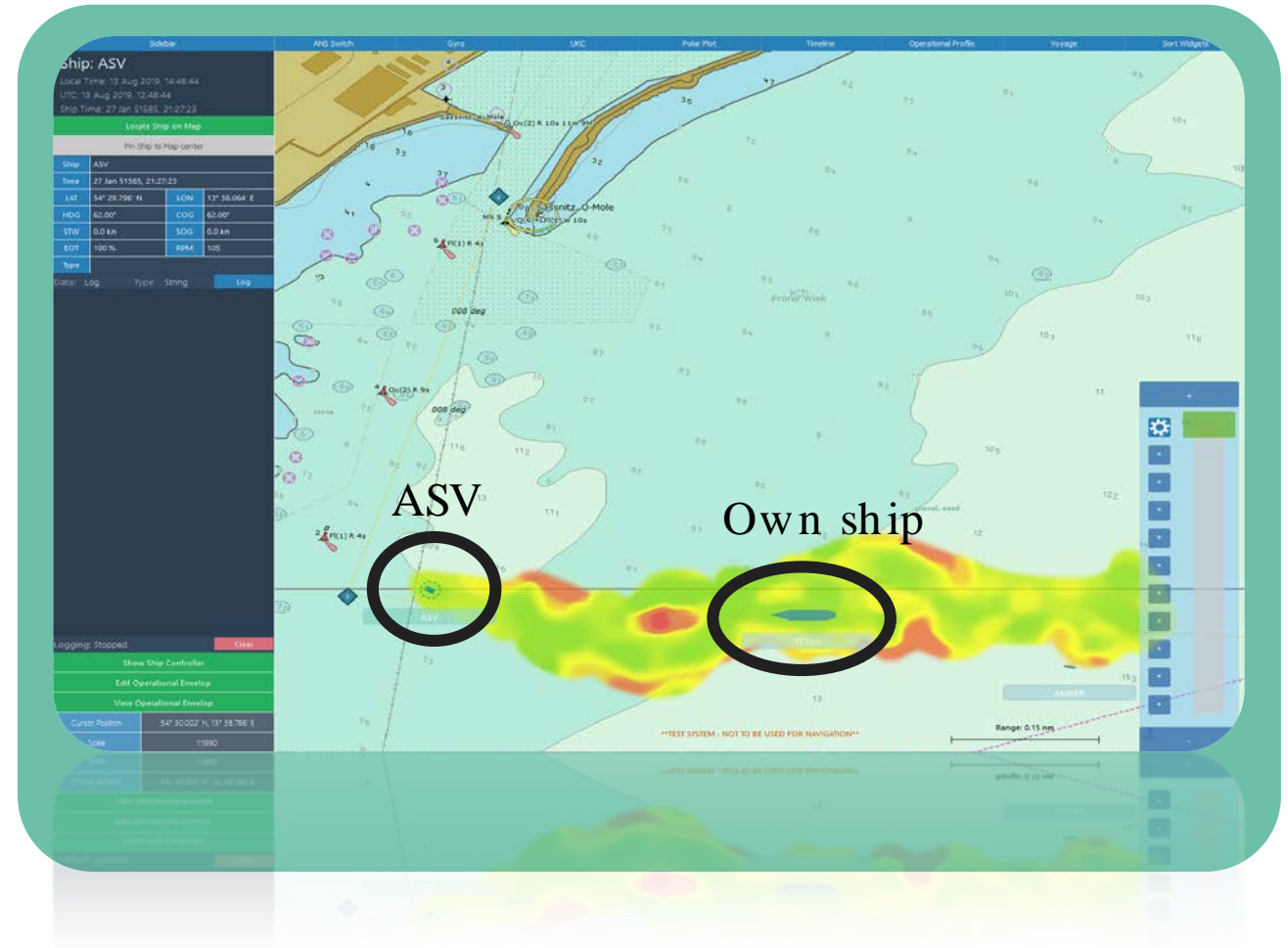
Autonomous Navigation System

Virtual Full Scale Simulation

2. Integrate ASV into simulation

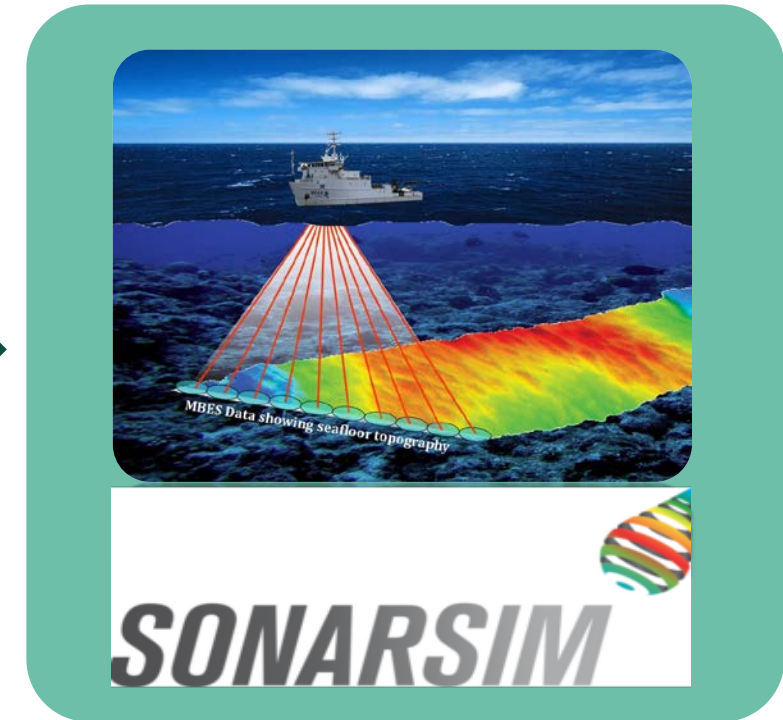
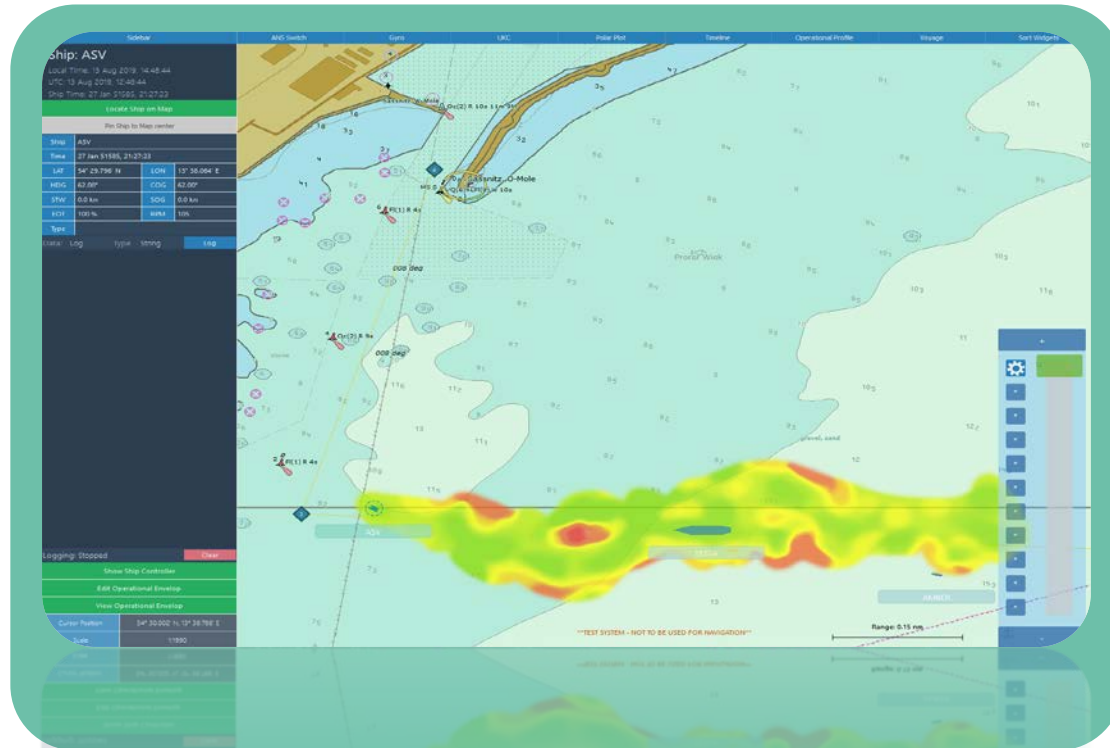
ANS

- AIS messages from SHS
- Harsh weather controller
- Collision avoidance
- Autopilot
- Can control multiple ships



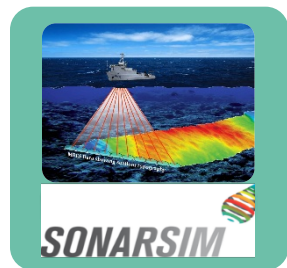
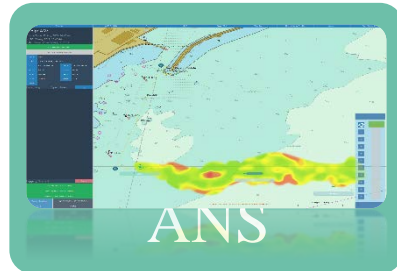
Virtual Full Scale Simulation

3. Create realistic depth maps of port approach



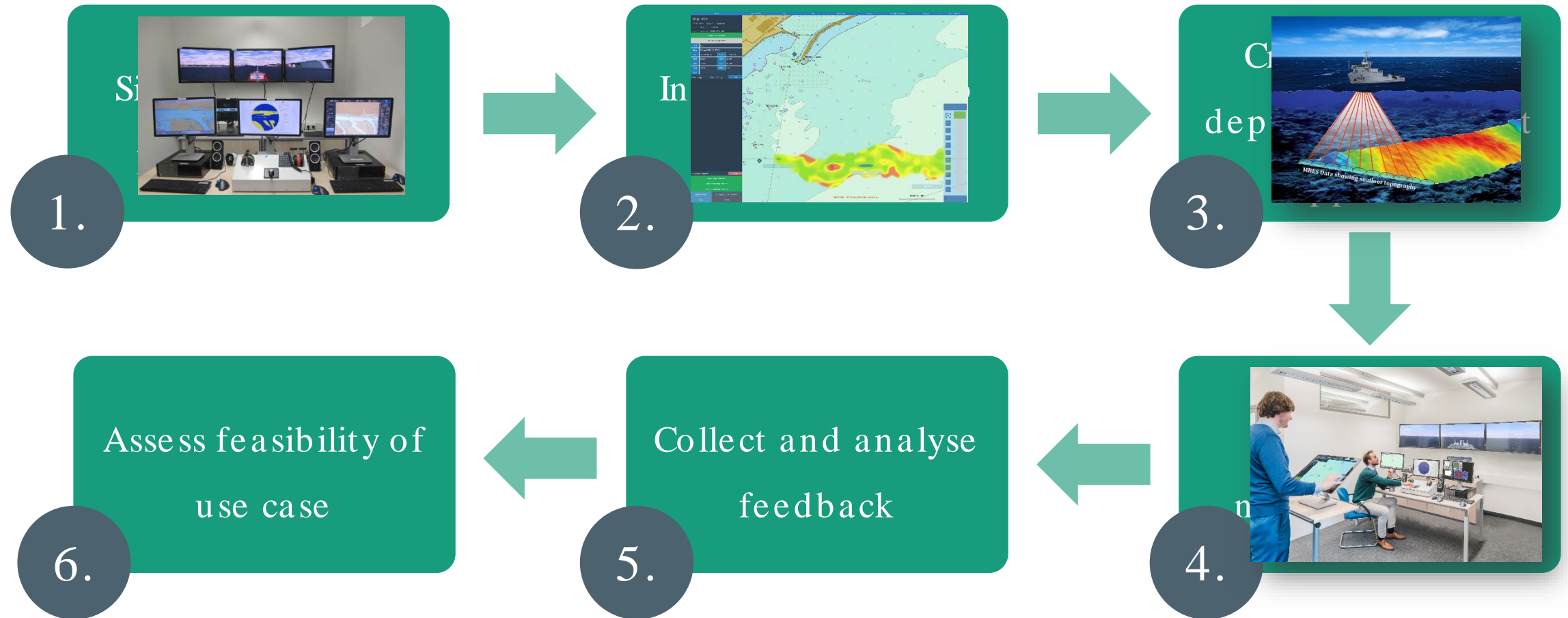
Virtual Full Scale Simulations

4. Exercise with nautical officers



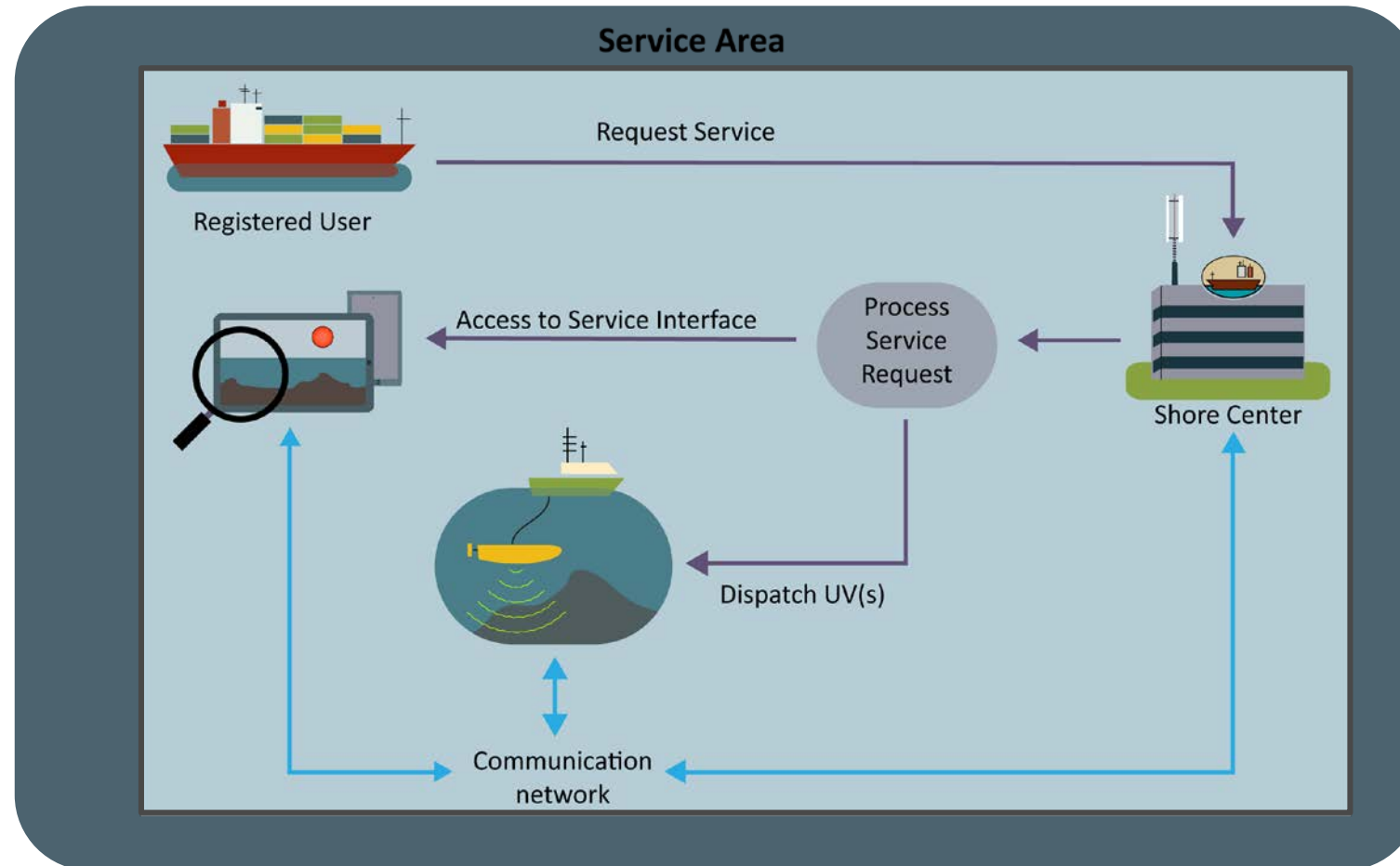
Virtual Full Scale Simulations

5. Feedback and 6. Evaluation



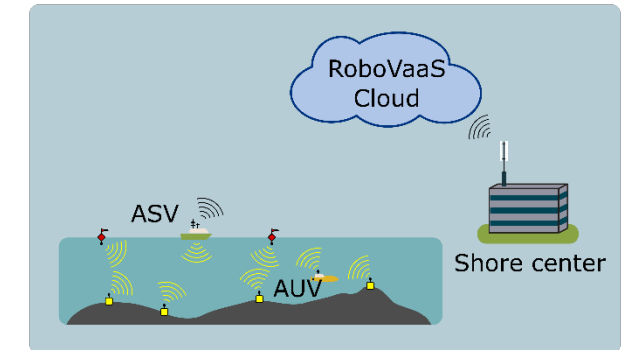
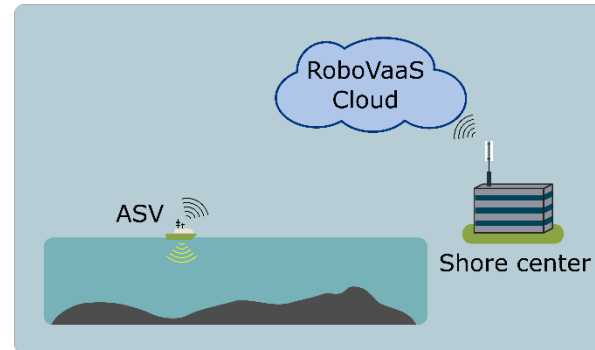
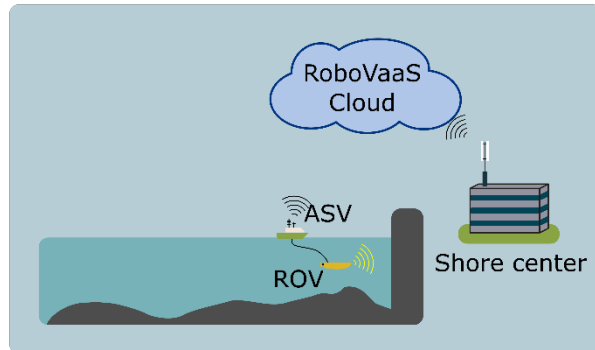
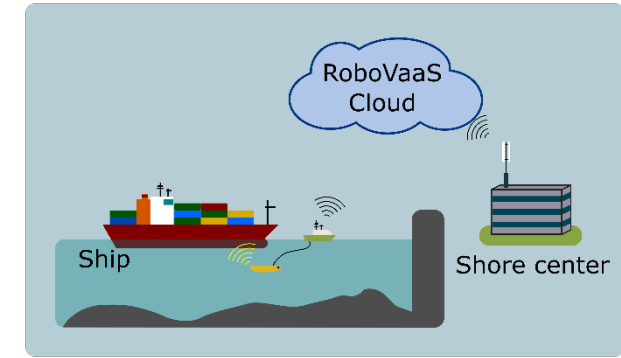
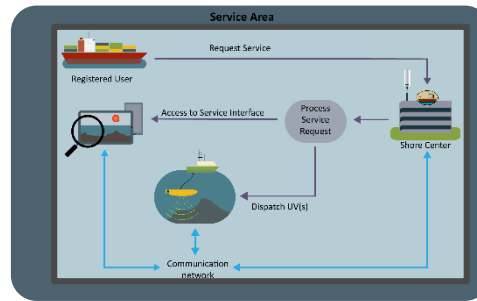
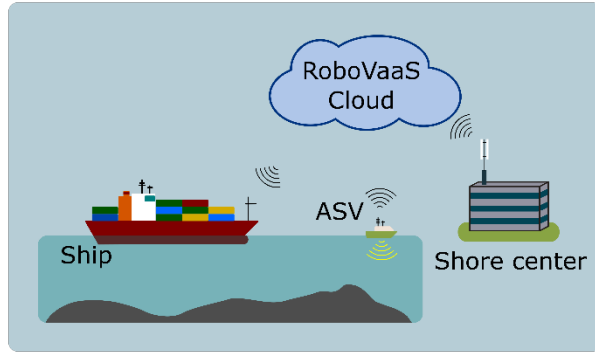
RoboVaaS – anti grounding use case

the service design



RoboVaaS

the five use cases





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References

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- [2] 5. Bürgerschaft HH, *Schriftliche Kleine Anfrage des Abgeordneten Michael Kruse (FDP) vom 19.03.15 und Antwort des Senats*, B.d.F.u.H. Hamburg, Editor. 2015
- [3] Köster F, T. Thies, The evolution of the Port of Hamburg from a hydrographic perspective, *Hydrographische Nachrichten*, 100, pp. 48-52, 2015
- [4] <https://www.hafen-hamburg.de/en/news/container-vessel-runs-aground-on-the-river-elbe---34489>